MATLAB Suite for Startups

MATLAB
Parallel Computing Toolbox
MATLAB Test
Stateflow
Requirements Toolbox

Math and Optimization
Curve Fitting Toolbox
Optimization Toolbox
Global Optimization Toolbox
Symbolic Math Toolbox
Mapping Toolbox
Partial Differential Equation Toolbox

AI, Data Science, and Statistics
Statistics and Machine Learning Toolbox
Deep Learning Toolbox
Deep Learning HDL Toolbox
Reinforcement Learning Toolbox
Text Analytics Toolbox
Predictive Maintenance Toolbox

Code Generation
MATLAB Coder
Fixed-Point Designer
GPU Coder
Deep Learning HDL Toolbox
C2000 Microcontroller Blockset

Application Deployment
MATLAB Compiler
MATLAB Compiler SDK

Database Access and Reporting
Database Toolbox
MATLAB Report Generator

Signal Processing
Signal Processing Toolbox
Phased Array System Toolbox
Radar Toolbox
DSP System Toolbox
Audio Toolbox
Wavelet Toolbox

Image Processing and Computer Vision
Image Processing Toolbox
Computer Vision Toolbox
Lidar Toolbox
Medical Imaging Toolbox

Automotive
Automated Driving Toolbox
Vehicle Network Toolbox

Control Systems
Control System Toolbox
System Identification Toolbox
Robust Control Toolbox
Model Predictive Control Toolbox
Fuzzy Logic Toolbox

Test & Measurement
Data Acquisition Toolbox
Instrument Control Toolbox
Image Acquisition Toolbox
Industrial Communication Toolbox

RF and Mixed Signal
Antenna Toolbox
RF Toolbox
RF PCB Toolbox
Sensor Fusion and Tracking Toolbox
SerDes Toolbox
Signal Integrity Toolbox

Wireless Communications
Bluetooth Toolbox
Communications Toolbox
WLAN Toolbox
LTE Toolbox
5G Toolbox
Satellite Communications Toolbox
Wireless Testbench

Autonomous Systems
Robotics System Toolbox
UAV Toolbox
Navigation Toolbox
ROS Toolbox

FPGA and ASIC Design
Filter Design HDL Coder
HDL Coder
HDL Verifier
DSP HDL Toolbox
Vision HDL Toolbox

Aerospace
Aerospace Toolbox

Computational Finance
Econometrics Toolbox
Financial Toolbox
Datafeed Toolbox
Spreadsheet Link
Financial Instruments Toolbox
Risk Management Toolbox

Computational Biology
Bioinformatics Toolbox
SimBiology

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